## 6<sup>TH</sup> SEM. /MECHANICAL/ 2024(W)

## **TH4** Industrial Robotics & Automation

Full Marks: 80			arks: 80 Tin	e- 3 Hrs
			Answer any five Questions including Q No.1& 2	
			Figures in the right hand margin indicates marks	
	1.		Answer All questions	2 x 10
		a.	What is the function of robot controller?	
		b.	State the use of sensor.	
		c.	Define Robot.	
		d.	What is end effector?	
		e.	State the function of stepper motor.	
		f.	What is servomotor?	
		g.	Write down two applications of robot sensor.	
		h.	What is VAL programming?	
		i.	Define proximity sensor.	
		j.	What is VAL programming? Define proximity sensor. Define teach pendant programming.  Answer <b>Any Six</b> Questions	
	2.		Answer Any Six Questions	5 x 6
		a.	Discuss about the safety measures in robotics.	
		b.	Describe a spray painting booth for painting automobiles cars using a suitable	
			spray painting robot.	
		c.	Differentiate between open loop and closed loop controller.	
		d.	Define Joint. Explain about the various joints of robot.	
		e.	Find out $x_1$ and $y_1$ of a 2DOF 2- D manipulator of a robot where $\theta_1$ and $\theta_2$ are the joint angles.	ie
		f.	What are the advantages and disadvantages of robots?	
		g	What are the principle and application of piezo electric sensor?	1
			Answer <b>Any Three</b> Questions	
	3.		Explain application of Robot vision system.	10
	<i>J</i> .			
	4.		Describe working principle and construction of Videocon camera.	10
1.7	). 6		Write down the robotic applications in manufacturing industry.	10
2707	6. 7.		Describe classification of Robots  Evaluin about the hydraulic actuators system	10
7	1.		Explain about the hydraulic actuators system.	10