



**KIIT POLYTECHNIC**

**LECTURE NOTES**

**ON**

**ENGG. MATH -III**

**PART-2**

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## CHAPTER-3 MATRICES

A rectangular arrangement of  $mn$  numbers with ' $m$ ' horizontal lines (rows) and ' $n$ ' vertical lines (columns) is known as matrix of order  $m \times n$  or ( $m$  by  $n$ ).

$$\text{Ex: } A = \begin{bmatrix} 3 & 2 & -1 \\ 3 & 5 & 1 \\ 2 & 4 & 3 \end{bmatrix}_{3 \times 3}$$

Note: An element occurring in the  $i$ th row and  $j$ th column of a matrix  $A$  will be called ( $i, j$ )th element. It is denoted by  $a_{ij}$ .

$$\text{Ex: } A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix}_{2 \times 3}$$

It is a matrix of order  $2 \times 3$  with general elements.

### Row matrix

A matrix having only one row is known as row matrix.

$$\text{Ex: } [2 \quad -1 \quad 3]_{1 \times 3}$$

### Column matrix

A matrix having only one column is known as column matrix.

$$\text{Ex: } \begin{bmatrix} 1 \\ 2 \\ -8 \\ 4 \end{bmatrix}_{4 \times 1}$$

### Null matrix or Zero matrix

If all the elements of a matrix are zero then it is called null matrix. It is denoted by  $O_{m \times n}$ .

$$\text{Ex: } \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}_{2 \times 3}$$

### Square matrix

If the number of rows and column of a matrix are equal then it is called square matrix.

i.e  $m = n$

$$\text{Ex: } A = \begin{bmatrix} 1 & 2 & 2 \\ -3 & 4 & -1 \\ 3 & 6 & 1 \end{bmatrix}_{3 \times 3}$$

### Rectangular matrix

If the number of rows and column of a matrix are not equal then it is called rectangular matrix.

i.e  $m \neq n$

$$\text{Ex: } A = \begin{bmatrix} 1 & 2 & -3 \\ 4 & 2 & 1 \end{bmatrix}_{2 \times 3}$$

### Diagonal matrix

A square matrix is said to be a diagonal matrix if all the diagonal elements are present but non diagonal elements are zero.

$$\text{Ex: } A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix}_{3 \times 3}$$

### Scalar matrix

A square matrix is said to be a scalar matrix if all the diagonal elements are same but non diagonal elements are zero.

$$\text{Ex: } A = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}_{3 \times 3}$$

### Identity matrix or unit matrix

A square matrix is said to be an unit matrix if all the diagonal elements are unity (1) but non diagonal elements are zero. It is denoted by  $I_n$  or  $I$ .

$$\text{Ex: } I_3 \text{ or } I = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}_{3 \times 3} \qquad I_2 \text{ or } I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

### Upper Triangular matrix

A square matrix is said to be an upper triangular matrix if all the elements below the main diagonal are zero.

$$\text{Ex: } A = \begin{bmatrix} 1 & 2 & 7 \\ 0 & -2 & 6 \\ 0 & 0 & 3 \end{bmatrix}_{3 \times 3}$$

Lower Triangular matrix

A square matrix is said to be a lower triangular matrix if all the elements above the main diagonal are zero.

$$\text{Ex: } A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & -2 & 0 \\ 5 & 7 & 3 \end{bmatrix}_{3 \times 3}$$

comparable matrix

Two matrices A and B are said to be comparable if they have same order.

$$\text{Ex: } A = \begin{bmatrix} 1 & -2 & 3 \\ 4 & 1 & 7 \end{bmatrix}_{2 \times 3} \quad B = \begin{bmatrix} 1 & a & b \\ c & d & 7 \end{bmatrix}_{2 \times 3}$$

Equal matrices

Two matrices A and B are said to be equal if they have same order and their corresponding elements are equal.

$$A = \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix}_{2 \times 2} \quad A = \begin{bmatrix} a_3 & b_3 \\ a_4 & b_4 \end{bmatrix}_{2 \times 2}$$

$$A = B \text{ iff } a_1 = a_3, b_1 = b_3, a_2 = a_4, b_2 = b_4$$

$$\text{Ex: Find the value of } x \text{ and } y \text{ if } \begin{bmatrix} x & 2y \\ 3 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 3 & -2 \end{bmatrix}$$

$$\text{Ans: Given } \begin{bmatrix} x & 2y \\ 3 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 3 & -2 \end{bmatrix}$$

$$x = 1, \quad 2y = 4 \Rightarrow y = 2$$

Matrix Addition

If A and B are two comparable matrices each of order  $m \times n$  then the addition  $A + B$  be a matrix obtained by adding the corresponding element of A and B.

$$\text{Ex: } A = \begin{bmatrix} 1 & -2 & 3 \\ 4 & 1 & 7 \end{bmatrix}_{2 \times 3} \quad B = \begin{bmatrix} 1 & 5 & 5 \\ 2 & 6 & -1 \end{bmatrix}_{2 \times 3}$$

$$\text{Ans: } A + B = \begin{bmatrix} 1 & -2 & 3 \\ 4 & 1 & 7 \end{bmatrix}_{2 \times 3} + \begin{bmatrix} 1 & 5 & 5 \\ 2 & 6 & -1 \end{bmatrix}_{2 \times 3} = \begin{bmatrix} 1+1 & -2+5 & 3+5 \\ 4+2 & 1+6 & 7-1 \end{bmatrix} = \begin{bmatrix} 2 & 3 & 8 \\ 6 & 7 & 6 \end{bmatrix}_{2 \times 3}$$

Scalar multiplication of a matrix

If A be a matrix and k be a scalar then the scalar multiplication of a matrix obtained by multiplying each element of A by k. It is denoted by  $kA$ .

$$\text{Ex: } A = \begin{bmatrix} 1 & 4 \\ 3 & -2 \end{bmatrix}$$

$$2A = 2 \begin{bmatrix} 1 & 4 \\ 3 & -2 \end{bmatrix} = \begin{bmatrix} 2 & 8 \\ 6 & -4 \end{bmatrix}$$

### Transpose of a matrix

If  $A$  be a matrix of order  $m \times n$  then the matrix obtained by changing the rows and columns then it is called transpose of a matrix. It is denoted by  $A^T$  or  $A'$  and the order of  $A^T$  is  $n \times m$ .

$$\text{Ex: } A = \begin{bmatrix} 1 & 4 \\ 3 & -2 \end{bmatrix}$$

$$A^T = \begin{bmatrix} 1 & 4 \\ 3 & -2 \end{bmatrix}^T = \begin{bmatrix} 1 & 3 \\ 4 & -2 \end{bmatrix}$$

### Matrix multiplication

#### Existence of the product of two matrices

The product of two matrices  $A$  and  $B$  will be exist if the number of columns in the 1st matrix ( $A$ ) is equal to the number of rows in the 2nd matrix ( $B$ ).

If  $A$  be a matrix of order  $m \times n$  and  $B$  be a matrix of order  $n \times p$  then  $AB$  be a matrix of order  $m \times p$ .

$$\text{Let } A = [ ]_{m \times n} \quad B = [ ]_{n \times p} \quad AB = [ ]_{m \times p}$$

$$\text{Note: } AI = A = IA$$

$$AA = A^2$$

$$II = I^2 = I$$

### Singular matrix

A square matrix ' $A$ ' is said to be a singular matrix if  $\det.A$  or  $|A| = 0$ .

$$\text{Ex: } A = \begin{vmatrix} 2 & 3 \\ 4 & 6 \end{vmatrix} = 12 - 12 = 0$$

### Non - Singular matrix

A square matrix ' $A$ ' is said to be a nonsingular matrix if  $\det.A$  or  $|A| \neq 0$ .

$$\text{Ex: } A = \begin{vmatrix} 3 & 2 \\ 4 & 4 \end{vmatrix} = 12 - 8 = 4 \neq 0$$

Rank of a matrix

The rank of a matrix is the largest order of any non vanishing minor of the matrix.

OR

The rank of a matrix is the maximum number L.I (Linear independent) rows or columns of the matrix.

OR

The number of non zero rows or columns of a triangular matrix is known as rank of a matrix.

Rank of a matrix is denoted by  $\rho(A)$  or  $r(A)$

How to find the rank of a matrix

1. Let the given matrix is A

2. Before finding rank check the pivot element ( $a_{11} \neq 0$ ) (i.e the 1st element in the matrix not zero)

3. If the pivot element ( $a_{11} = 0$ ) then interchange any two rows or columns.

4. Transfer all the elements below the pivot elements to '0' and reduce the matrix to an upper triangular matrix form.

5. After upper triangular matrix (rank of matrix = number of non zero rows or columns)

Note : If we interchange any two rows or columns of a matrix then the rank of a matrix remains unchanged.

Note :

1. If all minor of a matrix of order  $(r+1)$  are zero then its rank is  $\leq r$ .

2. Rank of nth order non singular matrix is n.

3. Rank of nth order singular matrix is  $< n$ .

4. Rank of nth order square matrix is  $\leq n$ .

5. Rank of nth order unit matrix is n.

6. Rank of a matrix having order  $m \times n$

(a) If  $m > n$  then rank is  $\leq n$

(b) If  $m < n$  then rank is  $\leq m$

(c) If  $m = n$  then rank is  $\leq m = n$

7. The rank of null matrix is zero.

Ex : Find the rank of the matrix  $\begin{bmatrix} 2 & 3 \\ 4 & 6 \end{bmatrix}$

Ans :  $A = \begin{bmatrix} 2 & 3 \\ 4 & 6 \end{bmatrix}$

$|A| = \begin{vmatrix} 2 & 3 \\ 4 & 6 \end{vmatrix} = 0$  , the 2nd order minor vanishes. so the rank of the matrix is 1.

Ex: Find the rank of the matrix  $\begin{bmatrix} 1 & 2 & 3 \\ 1 & 4 & 2 \\ 2 & 6 & 5 \end{bmatrix}$

Ans:  $\begin{bmatrix} 1 & 2 & 3 \\ 1 & 4 & 2 \\ 2 & 6 & 5 \end{bmatrix}$

(Here the 3rd order determinant vanishes.)

$$R_2 \rightarrow R_2 - R_1, R_3 \rightarrow R_3 - 2R_1$$

$$\approx \begin{bmatrix} 1 & 2 & 3 \\ 0 & 2 & -1 \\ 0 & 2 & -1 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_2$$

$$\approx \begin{bmatrix} 1 & 2 & 3 \\ 0 & 2 & -1 \\ 0 & 0 & 0 \end{bmatrix} \text{ (two non zero rows and one zero row are present after upper triangular matrix)}$$

Hence the rank of the matrix is 2 i.e.  $r(A) = 2$ .

Ex: Find the rank of the matrix  $\begin{bmatrix} 4 & 2 & 3 \\ 8 & 4 & 6 \\ -2 & -1 & -1.5 \end{bmatrix}$

Ans:  $\begin{bmatrix} 4 & 2 & 3 \\ 8 & 4 & 6 \\ -2 & -1 & -1.5 \end{bmatrix}$

(Here the 3rd order determinant vanishes.)

$$R_2 \rightarrow R_2 - 2R_1, R_3 \rightarrow R_3 + \frac{1}{2}R_1$$

$$\approx \begin{bmatrix} 4 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \text{ (two zero rows and one non zero row are present after simplification)}$$

Hence the rank of the matrix is 1 i.e.  $r(A) = 1$ .

Ex: Find the rank of the matrix  $\begin{bmatrix} 3 & -1 & 2 \\ -6 & 2 & 4 \\ -3 & 1 & 2 \end{bmatrix}$



$$\text{Ans: } \begin{bmatrix} 3 & -1 & 2 \\ -6 & 2 & 4 \\ -3 & 1 & 2 \end{bmatrix}$$

(Here the 3rd order determinant vanishes.)

$$R_2 \rightarrow R_2 + 2R_1, R_3 \rightarrow R_3 + R_1$$

$$\approx \begin{bmatrix} 3 & -1 & 2 \\ 0 & 0 & 8 \\ 0 & 0 & 4 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - \frac{1}{2}R_2$$

$$\approx \begin{bmatrix} 3 & -1 & 2 \\ 0 & 0 & 8 \\ 0 & 0 & 0 \end{bmatrix}$$

Hence the rank of the matrix is 2 i.e.  $r(A) = 2$ .

$$\text{Ex: Find the rank of the matrix } \begin{bmatrix} 1 & 5 & 9 \\ 4 & 8 & 12 \\ 7 & 11 & 15 \end{bmatrix}$$

$$\text{Ex: Find the rank of the matrix } \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\text{Ex: Find the rank of the matrix (a) } \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix}, (b) \begin{bmatrix} 0 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix}, (c) \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 2 & -2 & 2 \end{bmatrix}$$

$$\text{Ex: Find the rank of the matrix } \begin{bmatrix} 1 & 2 & 3 & 0 \\ 2 & 4 & 3 & 2 \\ 3 & 2 & 1 & 3 \\ 6 & 8 & 7 & 5 \end{bmatrix}$$

$$\text{Ans: } \begin{bmatrix} 1 & 2 & 3 & 0 \\ 2 & 4 & 3 & 2 \\ 3 & 2 & 1 & 3 \\ 6 & 8 & 7 & 5 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - 2R_1, R_3 \rightarrow R_3 - 3R_1, R_4 \rightarrow R_4 - 6R_1$$

$$\approx \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & -3 & 2 \\ 0 & -4 & -8 & 3 \\ 0 & -4 & -11 & 5 \end{bmatrix}$$

$$R_4 \rightarrow R_4 - R_3 - R_2$$

$$\approx \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & -3 & 2 \\ 0 & -4 & -8 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Hence the rank of the matrix is 3 i.e.  $r(A) = 3$ .

Ex: Find the rank of the matrix  $\begin{bmatrix} 5 & 6 & 7 & 8 \\ 6 & 7 & 8 & 9 \\ 11 & 12 & 13 & 14 \\ 16 & 17 & 18 & 19 \end{bmatrix}$

Ans:  $\begin{bmatrix} 5 & 6 & 7 & 8 \\ 6 & 7 & 8 & 9 \\ 11 & 12 & 13 & 14 \\ 16 & 17 & 18 & 19 \end{bmatrix}$

$$C_2 \rightarrow C_2 - C_1, C_3 \rightarrow C_3 - C_2, C_4 \rightarrow C_4 - C_3$$

$$\approx \begin{bmatrix} 5 & 1 & 1 & 1 \\ 6 & 1 & 1 & 1 \\ 11 & 1 & 1 & 1 \\ 16 & 1 & 1 & 1 \end{bmatrix}$$

$$C_3 \rightarrow C_3 - C_2, C_4 \rightarrow C_4 - C_3$$

$$\approx \begin{bmatrix} 5 & 1 & 0 & 0 \\ 6 & 1 & 0 & 0 \\ 11 & 1 & 0 & 0 \\ 16 & 1 & 0 & 0 \end{bmatrix}$$

Hence the rank of the matrix is 2 i.e.  $r(A) = 2$ .

Ex: Find the rank of the matrix  $\begin{bmatrix} 2 & 3 & 4 \\ 4 & 3 & 1 \\ 1 & 2 & 4 \end{bmatrix}$

Ex: Find the rank of the matrix (a)  $\begin{bmatrix} 2 & -1 & 1 & 4 \\ 3 & -1 & 1 & 6 \\ 4 & -1 & 2 & 7 \\ -1 & 1 & -1 & 9 \end{bmatrix}$ , (b)  $\begin{bmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & -2 & 1 \\ 1 & -1 & 4 & 0 \\ -2 & 2 & 8 & 0 \end{bmatrix}$ , (c)  $\begin{bmatrix} 1 & 3 & 2 & 4 \\ 5 & 2 & 0 & 1 \\ 3 & -4 & -4 & -7 \\ -7 & 5 & 6 & 10 \end{bmatrix}$

Ex: Find the rank of the matrix  $\begin{bmatrix} 1 & 3 & 4 & 3 \\ 3 & 9 & 12 & 3 \\ 1 & 3 & 4 & 1 \end{bmatrix}_{3 \times 4}$

Ans:  $\begin{bmatrix} 1 & 3 & 4 & 3 \\ 3 & 9 & 12 & 3 \\ 1 & 3 & 4 & 1 \end{bmatrix}$  (The rank is either 3 or  $< 3$ )

$$R_2 \rightarrow R_2 - 3R_1, R_3 \rightarrow R_3 - R_1$$

$$\approx \begin{bmatrix} 1 & 3 & 4 & 3 \\ 0 & 0 & 0 & -6 \\ 0 & 0 & 0 & -2 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - \frac{1}{3}R_2$$

$$\approx \begin{bmatrix} 1 & 3 & 4 & 3 \\ 0 & 0 & 0 & -6 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Hence the rank of the matrix is 2 i.e.  $r(A) = 2$ .

Ex: Find the rank of the matrix (a)  $\begin{bmatrix} 1 & 2 & -1 & -4 \\ 2 & 4 & 3 & 5 \\ -1 & -2 & 6 & -7 \end{bmatrix}$ , (b)  $\begin{bmatrix} 8 & 1 & 3 & 6 \\ 0 & 3 & 2 & 2 \\ -8 & -1 & -3 & 4 \end{bmatrix}$  (c)  $\begin{bmatrix} 1 & 2 & 3 \\ 9 & 5 & 6 \\ 7 & 8 & 9 \\ 0 & 2 & 1 \end{bmatrix}$

consistent and inconsistent

If the solution of the system of linear equation exist then it is called consistent otherwise it is called inconsistent.

Consistency for system of linear equations

Let us consider the system of 'm' linear equation with 'n' unknowns

$$\left. \begin{aligned} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= d_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n &= d_2 \\ \dots & \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n &= d_m \end{aligned} \right\} \dots (1)$$

Now equation (1) can be written in the form of  $AX = B$

$$\text{Where } A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}, \quad X = \begin{bmatrix} x_1 \\ x_2 \\ \cdot \\ \cdot \\ x_n \end{bmatrix}, \quad B = \begin{bmatrix} d_1 \\ d_2 \\ \cdot \\ \cdot \\ d_m \end{bmatrix}$$

Here A is called coefficient matrix.

$$\text{Let } K = \left[ \begin{array}{cccc|c} a_{11} & a_{12} & \dots & a_{1n} & d_1 \\ a_{21} & a_{22} & \dots & a_{2n} & d_2 \\ \dots & \dots & \dots & \dots & \cdot \\ a_{m1} & a_{m2} & \dots & a_{mn} & d_m \end{array} \right] \text{ which is called augmented matrix .}$$

Rouche's Theorem

The system of equation is consistent iff the rank of A and K are equal otherwise the system of equation is inconsistent.

Note :

- (1) If system of equation is consistent then it gives either unique solution or infinite solution. i.e it has at least one solution.
- (2) If system of equation is inconsistent then it gives no solution.

procedure for the test of consistency

Let the rank of coefficient matrix  $(A) = r$  and the rank of augmented matrix  $(K) = r'$

Number of variables =  $n$

No solution

If  $r \neq r'$  then equations are inconsistent and gives no solution.

Unique solution

(2) If  $r = r' = n$  then equations are consistent and gives unique solution.

Infinite solution

(3) If  $r = r' < n$  then equations are consistent and gives infinite solution.

Ex:

$$\text{Test the consistency } 4x - 2y + 6z = 8$$

$$x + y - 3z = -1$$

$$15x - 3y + 9z = 21$$

Ans:

The augmented matrix is

$$K = \left[ \begin{array}{ccc|c} 4 & -2 & 6 & 8 \\ 1 & 1 & -3 & -1 \\ 15 & -3 & 9 & 21 \end{array} \right]$$

$$\left\{ \text{Here } A = \left[ \begin{array}{ccc} 4 & -2 & 6 \\ 1 & 1 & -3 \\ 15 & -3 & 9 \end{array} \right] \right\}$$

$R_1 \leftrightarrow R_2$  (Two rows are interchanged)

$$\approx \left[ \begin{array}{ccc|c} 1 & 1 & -3 & -1 \\ 4 & -2 & 6 & 8 \\ 15 & -3 & 9 & 21 \end{array} \right]$$

$R_2 \rightarrow R_2 - 4R_1, R_3 \rightarrow R_3 - 15R_1$

$$\approx \left[ \begin{array}{ccc|c} 1 & 1 & -3 & -1 \\ 0 & -6 & 18 & 12 \\ 0 & -18 & 54 & 36 \end{array} \right]$$

$R_3 \rightarrow R_3 - 3R_2$

$$\approx \left[ \begin{array}{ccc|c} 1 & 1 & -3 & -1 \\ 0 & -6 & 18 & 12 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

here rank of  $A = 2$  and rank of  $K = 2, n = 3$

So it is consistent and gives infinite solution.

$$\text{Now } -6y + 18z = 12 \Rightarrow y - 3z = -2 \Rightarrow y = 3z - 2 \dots \dots (1)$$

$$\text{Again } x + y - 3z = -1 \Rightarrow x - 2 = -1 \Rightarrow x = 1 \text{ where } z \text{ is a parameter.}$$

Ex:

$$\begin{aligned} \text{Test the consistency } 2x - 3y + 7z &= 5 \\ 3x + y - 3z &= 13 \\ 2x + 19y - 47z &= 32 \end{aligned}$$

Ans:

The augmented matrix is

$$K = \left[ \begin{array}{ccc|c} 2 & -3 & 7 & 5 \\ 3 & 1 & -3 & 13 \\ 2 & 19 & -47 & 32 \end{array} \right]$$

$$\left\{ \text{Here } A = \begin{bmatrix} 2 & -3 & 7 \\ 3 & 1 & -3 \\ 2 & 19 & -47 \end{bmatrix} \right\}$$

$$R_2 \rightarrow 2R_2 - 3R_1, R_3 \rightarrow R_3 - R_1$$

$$\approx \left[ \begin{array}{ccc|c} 2 & -3 & 7 & 5 \\ 0 & 11 & -27 & 11 \\ 0 & 22 & -54 & 27 \end{array} \right]$$

$$R_3 \rightarrow R_3 - 2R_2$$

$$\approx \left[ \begin{array}{ccc|c} 2 & -3 & 7 & 5 \\ 0 & 11 & -27 & 11 \\ 0 & 0 & 0 & 5 \end{array} \right]$$

here rank of  $A = 2$  and rank of  $K = 3, n = 3$

So it is inconsistent and gives no solution.

Ex:

$$\begin{aligned} \text{Test the consistency } 2x - 3y + z &= 1 \\ x + 2y - 3z &= 4 \\ 4x - y - 2z &= 8 \end{aligned}$$

Ans:

The augmented matrix is

$$K = \left[ \begin{array}{ccc|c} 2 & -3 & 1 & 1 \\ 1 & 2 & -3 & 4 \\ 4 & -1 & -2 & 8 \end{array} \right]$$

$$\left\{ \text{Here } A = \begin{bmatrix} 2 & -3 & 1 \\ 1 & 2 & -3 \\ 4 & -1 & -2 \end{bmatrix} \right\}$$

$$R_2 \rightarrow 2R_2 - R_1, R_3 \rightarrow R_3 - 2R_1$$

$$\approx \left[ \begin{array}{ccc|c} 2 & -3 & 1 & 1 \\ 0 & 7 & -7 & 7 \\ 0 & 5 & -4 & 6 \end{array} \right]$$

$$R_3 \rightarrow 7R_3 - 5R_2$$

$$\approx \left[ \begin{array}{ccc|c} 2 & -3 & 1 & 1 \\ 0 & 7 & -7 & 7 \\ 0 & 0 & 7 & 7 \end{array} \right]$$

here rank of  $A = 3$  and rank of  $K = 3, n = 3$

So it is consistent and gives unique solution.

$$\text{Now } 7z = 7 \Rightarrow z = 1$$

$$7y - 7z = 7 \Rightarrow y - z = 1 \Rightarrow y = 1 + z = 1 + 1 = 2$$

$$2x - 3y + z = 1 \Rightarrow 2x - 6 + 1 = 1 \Rightarrow 2x = 6 \Rightarrow x = 3$$

Ex:

Test the consistency and if possible then find solution

$$(a) \quad x + 2y - z = 6$$

$$3x - y - 2z = 3$$

$$4x + 3y + z = 9$$

$$(b) \quad 4x + 3y + 2z = -7$$

$$2x + y - 4z = -1$$

$$x + 2y + z = 1$$

$$(c) \quad 2x - 3y + 7z = 5$$

$$5x - 2y + 4z = 18$$

$$2x + 19y - 47z = 32$$

Ex:

Test the consistency and if possible then find solution

$$x + 2y + z = 3$$

$$2x + 3y + 2z = 5$$

$$3x - 5y + 5z = 2$$

$$3x + 9y - z = 4$$

Ans:

The augmented matrix is

$$K = \left[ \begin{array}{ccc|c} 1 & 2 & 1 & 3 \\ 2 & 3 & 2 & 5 \\ 3 & -5 & 5 & 2 \\ 3 & 9 & -1 & 4 \end{array} \right]$$

$$\left\{ \text{Here } A = \left[ \begin{array}{ccc} 1 & 2 & 1 \\ 2 & 3 & 2 \\ 3 & -5 & 5 \\ 3 & 9 & -1 \end{array} \right] \right\}$$

$$R_2 \rightarrow R_2 - 2R_1, R_3 \rightarrow R_3 - 3R_1, R_4 \rightarrow R_4 - 3R_1$$

$$\approx \left[ \begin{array}{ccc|c} 1 & 2 & 1 & 3 \\ 0 & -1 & 0 & -1 \\ 0 & -11 & 2 & -7 \\ 0 & 3 & -4 & -5 \end{array} \right]$$

$$R_3 \rightarrow R_3 - 11R_2, R_4 \rightarrow R_4 + 3R_2$$

$$\approx \left[ \begin{array}{ccc|c} 1 & 2 & 1 & 3 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & -4 & -8 \end{array} \right]$$

$$R_4 \rightarrow R_4 + 2R_3$$

$$\approx \left[ \begin{array}{ccc|c} 1 & 2 & 1 & 3 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

here rank of  $A = 3$  and rank of  $K = 3, n = 3$

So it is consistent and gives unique solution.

$$\text{Now } 2z = 4 \Rightarrow z = 2$$

$$-y = -1 \Rightarrow y = 1$$

$$x + 2y + z = 3 \Rightarrow x + 2 + 2 = 3 \Rightarrow x = -1$$

Ex:

Test the consistency and if possible then find solution

$$x + 5y + 7z = 15$$

$$2x + 3y + 4z = 11$$

$$x - 2y - 3z = -4$$

$$3x + 11y + 13z = 25$$



*Ex: Investigate for what value of  $\lambda$  and  $\mu$  the simultaneous equation*

$$x + y + z = 6$$

$$x + 2y + 3z = 10$$

$$x + 2y + \lambda z = \mu \quad \text{has (a) no solution, (b) a unique, (c) an infinite number of solution}$$

$$\text{Ans: Here } A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 2 & \lambda \end{bmatrix}, X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, B = \begin{bmatrix} 6 \\ 10 \\ \mu \end{bmatrix}$$

$$\text{Now } K = \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 1 & 2 & 3 & 10 \\ 1 & 2 & \lambda & \mu \end{array} \right]$$

$$R_2 \rightarrow R_2 - R_1, R_3 \rightarrow R_3 - R_1$$

$$\approx \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & \lambda - 3 & \mu - 10 \end{array} \right]$$

No solution

If  $\lambda = 3$  and  $\mu \neq 10$  then rank of  $A = 2$ , rank of  $K = 3$

Unique solution

If  $\lambda \neq 3$  and  $\mu$  be any value then rank of  $A = \text{rank of } K = 3$

Infinite solution

If  $\lambda = 3$  and  $\mu = 10$  then rank of  $A = \text{rank of } K = 2 < n (n = 3)$

*Ex: Show that the equations*

$$3x + 4y + 5z = a$$

$$4x + 5y + 6z = b$$

$$5x + 6y + 7z = c \quad \text{do not have a solution unless } a + c = 2b.$$

$$\text{Ans: Here } A = \begin{bmatrix} 3 & 4 & 5 \\ 4 & 5 & 6 \\ 5 & 6 & 7 \end{bmatrix}, X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, B = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$$\text{Now } K = \left[ \begin{array}{ccc|c} 3 & 4 & 5 & a \\ 4 & 5 & 6 & b \\ 5 & 6 & 7 & c \end{array} \right]$$

$$R_2 \rightarrow 3R_2 - 4R_1, R_3 \rightarrow 3R_3 - 5R_1$$

$$\approx \left[ \begin{array}{ccc|c} 3 & 4 & 5 & a \\ 0 & -1 & -2 & 3b-4a \\ 0 & -2 & -4 & 3c-5a \end{array} \right]$$

$$R_3 \rightarrow R_3 - 2R_2$$

$$\approx \left[ \begin{array}{ccc|c} 3 & 4 & 5 & a \\ 0 & -1 & -2 & 3b-4a \\ 0 & 0 & 0 & 3c-6b+3a \end{array} \right]$$

Rank of  $A = 2$

The system of equation is consistent if the rank of augmented matrix  $K = 2$

which is obtained if  $3c - 6b + 3a = 0$

$$\Rightarrow 3c + 3a = 6b \Rightarrow a + c = 2b$$

Hence the equation have no solution unless  $a + c = 2b$ .

### PREVIOUS YEAR QUESTIONS

Ex-1: Find the rank of the matrix  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 2 \\ 2 & 3 & 4 \end{bmatrix}$  (2006)

Ex-2: Test the consistency and hence solve

$$x + y + z = 6$$

$$x - y + 2z = 5$$

$$3x + y + z = 8$$

$$2x - 2y + 3z = 7 \quad (2006)$$

Ex-3: Write down the procedure to test the consistency of a system of equations in 'n' unknowns. (2007)

Ex-4: Determine the rank of the matrix

$$\begin{bmatrix} 3 & -1 & 2 \\ -6 & 2 & 4 \\ -3 & 1 & 2 \end{bmatrix} \quad (2007, 2004, 2003)$$

Ex-5: Define the rank of a matrix. (2005)

Ex-6: Ex: Investigate for what value of  $\lambda$  and  $\mu$  the simultaneous equation

$$x + y + z = 6$$

$$x + 2y + 3z = 10$$

$$x + 2y + \lambda z = \mu \quad \text{has (a) no solution, (b) a unique, (c) an infinite number of solution (2005)}$$

Ex-7: Write what you mean null matrix. (2004)

Ex-8: Find the rank of a matrix  $\begin{bmatrix} 1 & 2 & 3 & 2 \\ 2 & 3 & 5 & 1 \\ 1 & 3 & 4 & 5 \end{bmatrix}$  (2002)

Ex-9: Find the rank of the matrix  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$  (2008)

Ex-10: Investigate for what values of  $\lambda$  and  $\mu$  the simultaneous equations

$$x + y + z = 6$$

$$x + 2y + 3z = 10$$

$x + 2y + \lambda z = \mu$  have (a) no solution (b) a unique solution (c) an infinite number of solution

(2008)

Ex-11: Find the rank of the matrix  $\begin{bmatrix} 1 & 2 & 0 \\ 2 & 4 & 0 \\ 4 & 8 & 0 \end{bmatrix}$  (2009)

Ex-13: State Rouché's theorem. (2010)

Ex-14: Test the consistency and solve

$$5x + 3y + 7z = 4$$

$$3x + 26y + 2z = 9$$

$$7x + 2y + 10z = 5$$

(2010)

Ex-15: Find the rank of the matrix  $\begin{bmatrix} 1 & 2 & 0 \\ 2 & 4 & 0 \\ 4 & 8 & 2 \end{bmatrix}$  (2011)

Ex-16: Find the rank of the matrix  $\begin{bmatrix} 5 & 6 & 7 & 8 \\ 6 & 7 & 8 & 9 \\ 11 & 12 & 13 & 14 \\ 16 & 17 & 18 & 19 \end{bmatrix}$  (2011)

Ex-17: Find the rank of the matrix  $\begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$  (2010 old)

# CHAPTER-3

## LAPLACE TRANSFORMS

Def<sup>n</sup>: Let  $f(t)$  be the real valued function of  $t$ ,  $t > 0$ . Then Laplace transform of  $f(t)$  is given by  $L\{f(t)\} = \int_0^{\infty} e^{-st} f(t) dt$ ,

where  $s$  is parameter may be real or complex

Formulas: (Laplace Transformation of some simple functions)

(i) Laplace Transform of constant function :

Let  $f(t)=k$ , where  $k$  is constant

Then Laplace transform of  $f(t)$  is given by

$$L\{f(t)\}=L(k)=\frac{k}{s} \quad *$$

Ex :  $L(1)=1/s$ ,  $L(3)=3/s$ ,  $L(-3)=-3/s$ , .....etc

(ii) Laplace Transform of algebraic function:

Let  $f(t)=t^n$ ,  $n=0,1,2,\dots$

Then Laplace transform of  $f(t)$  is given by

$$L\{f(t)\}=L(t^n)=\frac{n!}{s^{n+1}}, \text{ where } n! \text{ is factorial of } n \quad *$$

$$n!=n(n-1)(n-2)\dots 2.1$$

i. e.  $5!=5.4.3.2.1=120$ ,  $4!=4.3.2.1=24$  .....etc

Ex:  $L(t)=1/s^2$ ,  $L(t^2)=2/s^3$ , .....

(iii) Laplace Transform of exponential function:

Let  $f(t)=e^{at}$ , where  $a$  is constant

Then Laplace transform of  $f(t)$  is given by

$$L\{f(t)\}=L(e^{at})=\frac{1}{s-a} \quad *$$

$$\text{Similarly, } L(e^{-at})=\frac{1}{s+a} \quad *$$

$$\text{Ex: } L(e^t)=\frac{1}{s-1}, L(e^{-t})=\frac{1}{s+1}, L(e^{-2t})=\frac{1}{s+2}, \dots\dots etc$$

(iv) Laplace Transform of trigonometric function:Let  $f(t) = \sin at$ Then Laplace transform of  $f(t)$  is given by

$$L(\sin at) = \frac{a}{s^2 + a^2}, \text{ where } a \text{ is constant} \quad *$$

$$\text{Ex: } L(\sin t) = \frac{1}{s^2 + 1}, L(\sin 2t) = \frac{2}{s^2 + 4}, L(\sin 5t) = \frac{5}{s^2 + 25} \dots \dots \text{etc}$$

Let  $f(t) = \cos at$ Then Laplace transform of  $f(t)$  is given by

$$L(\cos at) = \frac{s}{s^2 + a^2}, \text{ where } a \text{ is constant} \quad *$$

$$\text{Ex: } L(\cos t) = \frac{s}{s^2 + 1}, L(\cos 2t) = \frac{s}{s^2 + 4}, L(\cos 3t) = \frac{s}{s^2 + 9} \dots \dots \text{etc}$$

(v) Laplace Transform of hyperbolic function:Let  $f(t) = \sinh at$  (reads as sine hyperbolic)Then Laplace transform of  $f(t)$  is given by

$$L(\sinh at) = \frac{a}{s^2 - a^2}, \text{ where } a \text{ is constant} \quad *$$

$$\text{Ex: } L(\sinh t) = \frac{1}{s^2 - 1}, L(\sinh 2t) = \frac{2}{s^2 - 4}, L(\sinh 5t) = \frac{5}{s^2 - 25} \dots \dots \text{etc}$$

Let  $f(t) = \cosh at$  (reads as cosine hyperbolic)Then Laplace transform of  $f(t)$  is given by

$$L(\cosh at) = \frac{s}{s^2 - a^2}, \text{ where } a \text{ is constant} \quad *$$

$$\text{Ex: } L(\cosh t) = \frac{s}{s^2 - 1}, L(\cosh 3t) = \frac{s}{s^2 - 9}, L(\cosh 4t) = \frac{s}{s^2 - 16} \dots \dots \text{etc}$$

First Shifting Theorem:

If  $L\{f(t)\} = \bar{f}(s)$ , then  $L\{e^{at} f(t)\} = \bar{f}(s - a), s - a > 0$

Proof: From the def<sup>n</sup>, we have

$$L\{f(t)\} = \int_0^{\infty} e^{-st} f(t) dt = \bar{f}(s) \Rightarrow L\{e^{at} f(t)\} = \int_0^{\infty} e^{-st} \cdot e^{at} f(t) dt$$

$$= \int_0^{\infty} e^{-(s-a)t} f(t) dt = \bar{f}(s-a) \quad (\text{comparing def}^n)$$

Similarly

$$\text{If } L\{f(t)\} = \bar{f}(s), \text{ then } L\{e^{-at} f(t)\} = \bar{f}(s+a),$$

$$(i) \quad L(e^{at}) = \frac{1}{s-a} \left( \because L(1) = \frac{1}{s} \right)$$

$$(ii) \quad L(e^{at} t^n) = \frac{n!}{(s-a)^{n+1}}, n = 0, 1, 2, \dots$$

$$(iii) \quad L(e^{at} \sin bt) = \frac{b}{(s-a)^2 + b^2}$$

$$(iv) \quad L(e^{at} \cos bt) = \frac{s-a}{(s-a)^2 + b^2}$$

$$(v) \quad L(e^{at} \sinh bt) = \frac{b}{(s-a)^2 - b^2}$$

$$(vi) \quad L(e^{at} \cosh bt) = \frac{s-a}{(s-a)^2 - b^2}$$

Some trigonometric formula :

$$(i) \quad \sin(A+B) = \sin A \cos B + \cos A \sin B$$

$$(ii) \quad \sin(A-B) = \sin A \cos B - \cos A \sin B$$

$$(iii) \quad \cos(A+B) = \cos A \cos B - \sin A \sin B$$

$$(iv) \quad \cos(A-B) = \cos A \cos B + \sin A \sin B$$

$$(v) \quad \sin(A+B) + \sin(A-B) = 2 \sin A \cos B$$

$$(vi) \quad \sin(A+B) - \sin(A-B) = 2 \cos A \sin B$$

$$(vii) \quad \cos(A+B) + \cos(A-B) = 2 \cos A \cos B$$

$$(viii) \quad \cos(A-B) - \cos(A+B) = 2 \sin A \sin B$$

$$(ix) \quad \sin 2A = 2 \sin A \cos A$$

$$(x) \quad \cos 2A = \cos^2 A - \sin^2 A = 1 - 2 \sin^2 A = 2 \cos^2 A - 1$$

$$(xi) \quad \tan^{-1} x + \cot^{-1} x = \frac{\pi}{2}$$

$$(xii) \quad \sin^2 A = \frac{1 - \cos 2A}{2}, \sin^2 2A = \frac{1 - \cos 4A}{2}, \dots$$

$$(xiii) \quad \cos^2 A = \frac{1 + \cos 2A}{2}, \cos^2 2A = \frac{1 + \cos 4A}{2}, \dots$$

$$(xiv) \quad \sin^3 A = \frac{3 \sin A - \sin 3A}{4}, \cos^3 A = \frac{3 \cos A + \cos 3A}{4}$$

Some Derivative formula:

- (i)  $\frac{d}{dx}(\sin x) = \cos x, \frac{d}{dx}(\cos x) = -\sin x, \frac{d}{dx}(\sin 2x) = 2 \cos 2x, \frac{d}{dx}(\cos 3x) = -3 \sin 3x, \dots$
- (ii)  $\frac{d}{dx}(uv) = u \cdot \frac{dv}{dx} + v \cdot \frac{du}{dx}$  (product rule)
- (iii)  $\frac{d}{dx}\left(\frac{u}{v}\right) = \frac{v \cdot \frac{du}{dx} - u \cdot \frac{dv}{dx}}{v^2}$  (division rule) Some
- (iv)  $\frac{d}{dx}(\tan^{-1}x) = \frac{1}{1+x^2}, \frac{d}{dx}(\cot^{-1}x) = -\frac{1}{1+x^2}$
- 

Integration formula:

- (i)  $\int \sin x \, dx = -\cos x + c, \int \cos x \, dx = \sin x + c$
- (ii)  $\int \sin 2x \, dx = -\frac{\cos 2x}{2} + c, \int \cos 3x \, dx = \frac{\sin 3x}{3} + c, \dots$
- (iii)  $\int \frac{1}{1+x^2} \, dx = \tan^{-1}x + c, \int \frac{1}{x^2+a^2} \, dx = \frac{1}{a} \tan^{-1}\left(\frac{x}{a}\right) + c$
- 

Algebraic Properties of Laplace transformation:

- (i)  $L(u \pm v \pm w \pm \dots) = L(u) \pm L(v) \pm \dots$
- (ii)  $L(k \cdot f(t)) = k \cdot L(f(t))$ , where  $k$  is constant
- 

**Ex 1 : Find Laplace transforms of the following functions:**

- (i)  $1+t^2-3t$ , (ii)  $(1+t)^2$ , (iii)  $\cos t - 3\sin t$ , (iv)  $\sin^2 t$ , (v)  $\cos^2 t$   
 (vi)  $\sin^2 2t$ , (vii)  $\cos^2 3t$ , (viii)  $(\cos t - \sin t)^2$ , (ix)  $1+e^{-t}$ , (x)  $\sin 3t \cdot \cos 2t$   
 (xi)  $\cos 4t \cdot \cos t$ , (xii)  $\sin 3t \cdot \sin t$ , (xiii)  $\cos(at+b)$ , (xiv)  $\cosh 2t - \sinh t$   
 (xv)  $\sin^3 t$ , (xvi)  $\cos^3 t$ , (xvii)  $\sin^3 2t$ , (xviii)  $\cos^3 3t$ .

Sol<sup>n</sup>:

$$(i) \quad L(1+t^2-3t) = L(1) + L(t^2) - L(3t) = \frac{1}{s} + \frac{2!}{s^{2+1}} - 3 \cdot \frac{1}{s^2} = \frac{1}{s} + \frac{2}{s^3} - \frac{3}{s^2}$$

$$(ii) \quad L(1+t)^2 = L(1+2t+t^2) = L(1) + L(2t) + L(t^2) = \frac{1}{s} + \frac{2}{s^2} + \frac{2}{s^3}$$

$$(iii) \quad L(\cos t - 3 \sin t) = L(\cos t) - L(3 \sin t) = \frac{s}{s^2+1} - \frac{3}{s^2+1}$$

$$(iv) \quad L(\sin^2 t) = L\left(\frac{1-\cos 2t}{2}\right) = \frac{1}{2}\{L(1) - L(\cos 2t)\} = \frac{1}{2}\left(\frac{1}{s} - \frac{s}{s^2+4}\right)$$

$$(v) \quad L(\cos^2 t) = L\left(\frac{1+\cos 2t}{2}\right) = \frac{1}{2}\{L(1) + L(\cos 2t)\} = \frac{1}{2}\left(\frac{1}{s} + \frac{s}{s^2+4}\right)$$

$$(vi) \quad L(\sin^2 2t) = L\left(\frac{1-\cos 4t}{2}\right) = \frac{1}{2}\{L(1) - L(\cos 4t)\} = \frac{1}{2}\left(\frac{1}{s} - \frac{s}{s^2+16}\right)$$

$$(vii) \quad L(\cos^2 3t) = L\left(\frac{1+\cos 6t}{2}\right) = \frac{1}{2}\{L(1) + L(\cos 6t)\} = \frac{1}{2}\left(\frac{1}{s} + \frac{s}{s^2+36}\right)$$

$$(viii) \quad L(\cos t + \sin t)^2 = L(\cos^2 t + \sin^2 t + 2 \sin t \cdot \cos t) \\ = L(1 + \sin 2t) = L(1) + L(\sin 2t) = \frac{1}{s} + \frac{2}{s^2+4}$$

$$(ix) \quad L(1 + e^{-t}) = L(1) + L(e^{-t}) = \frac{1}{s} + \frac{1}{s+1}$$

$$(x) \quad L(\sin 3t \cdot \cos 2t) = \frac{1}{2}L(2 \sin 3t \cdot \cos 2t) \\ = \frac{1}{2}L\{\sin(3t+2t) + \sin(3t-2t)\} \\ = \frac{1}{2}L(\sin 5t + \sin t) = \frac{1}{2}\left(\frac{5}{s^2+25} + \frac{1}{s^2+1}\right)$$

$$(xi) \quad L(\cos 4t \cdot \cos t) = \frac{1}{2}L(2 \cos 4t \cdot \cos t) \\ = \frac{1}{2}L(\cos(4t+t) + \cos(4t-t)) \\ = \frac{1}{2}L(\cos 5t + \cos 3t) = \frac{1}{2}\left(\frac{s}{s^2+25} + \frac{s}{s^2+9}\right)$$



$$\begin{aligned}
 (xii) \quad L(\sin 3t \cdot \sin t) &= \frac{1}{2} L(2 \sin 3t \cdot \sin t) \\
 &= \frac{1}{2} L\{\cos(3t-t) - \cos(3t+t)\} \\
 &= \frac{1}{2} L(\cos 2t - \cos 4t) = \frac{1}{2} \left( \frac{s}{s^2+4} - \frac{s}{s^2+16} \right)
 \end{aligned}$$

$$\begin{aligned}
 (xiii) \quad L\{\cos(at+b)\} &= L(\cos at \cdot \cos b - \sin at \cdot \sin b) \\
 &= L(\cos at \cdot \cos b) - L(\sin at \cdot \sin b) \\
 &= \cos b \cdot \frac{s}{s^2+a^2} - \sin b \cdot \frac{a}{s^2+a^2}
 \end{aligned}$$

$$(xiv) \quad L\{\cosh 2t - \sinh t\} = L(\cosh 2t) - L(\sinh t) = \frac{s}{s^2-4} - \frac{1}{s^2-1}$$

$$(xv) \quad L(\sin^3 t) = L\left(\frac{3 \sin t - \sin 3t}{4}\right) = \frac{1}{4} \left( \frac{3}{s^2+1} - \frac{3}{s^2+9} \right)$$

$$(xvi) \quad L(\cos^3 t) = L\left(\frac{3 \cos t + \cos 3t}{4}\right) = \frac{1}{4} \left( \frac{3s}{s^2+1} + \frac{s}{s^2+9} \right)$$

$$\begin{aligned}
 (xvii) \quad L(\sin^3 2t) &= L\left(\frac{3 \sin 2t - \sin 6t}{4}\right) = \frac{1}{4} \left( 3 \cdot \frac{2}{s^2+4} - \frac{6}{s^2+36} \right) \\
 &= \frac{1}{4} \left( \frac{6}{s^2+4} - \frac{6}{s^2+36} \right)
 \end{aligned}$$

$$(xviii) \quad L(\cos^3 3t) = L\left(\frac{3 \cos 3t + \cos 9t}{4}\right) = \frac{1}{4} \left( \frac{3s}{s^2+9} + \frac{s}{s^2+81} \right)$$

### **Exercises-1**

Find Laplace transform of the following functions:

(i)  $2-3t+e^{2t}$

(ii)  $(1-t^2)^2$

(iii)  $(e^t+1)^2$

(iv)  $(\sin t - \cos t)^2$

(v)  $\sin^2 3t$

(vi)  $\cos^2 2t$

(vii)  $\sin 4t \cdot \cos 2t$

(viii)  $\cos 3t \cdot \cos 2t$

(ix)  $\sin 3t \cdot \sin 2t$

(x)  $\sin(at+b)$

(xi)  $\sin^3 3t$

**Ex 2: Find Laplace transform of the following functions**

- (i)  $te^{-t}$  (ii)  $t^2e^{2t}$  (iii)  $e^{2t}t^5$  (iv)  $e^{-t}\sin t$  (v)  $e^{2t}\cos 2t$  (vi)  $e^{3t}\sin^2 t$   
 (vii)  $e^{-2t}\cos^2 t$  (viii)  $e^{-4t}\sin 2t \cos t$  (ix)  $e^t \cos 3t \cos t$  (x)  $e^{-t}(\cosh 2t - \sinh t)$   
 (xi)  $(1+t)e^{-t}$

Sol<sup>n</sup>:

- (i) We have  $L(t) = \frac{1}{s^2}$   
 Using first shifting rule,  $L(te^{-t}) = \frac{1}{(s+1)^2}$  [i.e.  $s \rightarrow s - (-1) = s + 1$ ]
- (ii) We have  $L(t^2) = \frac{2!}{s^{2+1}} = \frac{2}{s^3}$   
 Using first shifting rule,  $L(t^2e^{2t}) = \frac{2}{(s-2)^3}$
- (iii) We have  $L(t^5) = \frac{5!}{s^{5+1}} = \frac{120}{s^6}$   
 Using first shifting rule,  $L(e^{2t}t^5) = \frac{120}{(s-2)^6}$
- (iv) We have  $L(\sin t) = \frac{1}{s^2 + 1}$   
 Using first shifting rule,  $L(e^{-t}\sin t) = \frac{1}{(s+1)^2 + 1} = \frac{1}{s^2 + 2s + 2}$
- (v) We have  $L(\cos 2t) = \frac{s}{s^2 + 4}$   
 Using first shifting rule,  $L(e^{2t}\cos 2t) = \frac{s-2}{(s-2)^2 + 4} = \frac{s-2}{s^2 - 4s + 8}$
- (vi) We have  $L(\sin^2 t) = L\left(\frac{1 - \cos 2t}{2}\right) = \frac{1}{2}\left(\frac{1}{s} - \frac{s}{s^2 + 4}\right)$   
 Using first shifting rule,  $L(e^{3t}\sin^2 t) = \frac{1}{2}\left(\frac{1}{s-3} - \frac{s-3}{(s-3)^2 + 4}\right)$
- (vii) We have  $L(\cos^2 t) = L\left(\frac{1 + \cos 2t}{2}\right) = \frac{1}{2}\left(\frac{1}{s} + \frac{s}{s^2 + 4}\right)$   
 Using first shifting rule,  $L(e^{-2t}\cos^2 t) = \frac{1}{2}\left(\frac{1}{s+2} + \frac{s+2}{(s+2)^2 + 4}\right)$

(viii) We have  $L(\sin 2t \cos t) = \frac{1}{2}L(2\sin 2t \cos t)$

$$= \frac{1}{2}L(\sin 3t + \sin t) = \frac{1}{2}\left(\frac{3}{s^2 + 9} + \frac{1}{s^2 + 1}\right)$$

Using first shifting rule,  $L(e^{-4t} \sin 2t \cos t) = \frac{1}{2}\left(\frac{3}{(s+4)^2 + 9} + \frac{1}{(s+4)^2 + 1}\right)$

(ix) We have  $L(\cos 3t \cos t) = \frac{1}{2}L(2\cos 3t \cos t)$

$$= \frac{1}{2}L(\cos 4t + \cos 2t) = \frac{1}{2}\left(\frac{s}{s^2 + 16} + \frac{s}{s^2 + 4}\right)$$

Using first shifting rule,  $L(e^t \cos 3t \cos t) = \frac{1}{2}\left(\frac{s-1}{(s-1)^2 + 16} + \frac{s-1}{(s-1)^2 + 4}\right)$

(x) We have  $L(\cosh 2t - \sinh t) = \left(\frac{s}{s^2 - 4} - \frac{1}{s^2 - 1}\right)$

Using first shifting rule,  $L\{e^{-t}(\cosh 2t - \sinh t)\} = \frac{s+1}{(s+1)^2 - 4} - \frac{1}{(s+1)^2 - 1}$

(xi) We have  $L(1+t) = \frac{1}{s} + \frac{1}{s^2}$

Using first shifting rule,  $L\{(1+t)e^{-t}\} = \frac{1}{s+1} + \frac{1}{(s+1)^2}$

### Exercises-2

Find Laplace transform of the following functions:

(i)  $te^{2t}$  (ii)  $t^3e^{-t}$  (iii)  $e^{-2t}\sin 3t$  (iv)  $e^t \cos 4t$  (v)  $e^{2t}\cos^2 2t$  (vi)  $e^{-t}\sin^2 3t$  (vii)  $e^{-t}\sin^3 t$   
 (viii)  $e^t \cos^3 t$  (ix)  $e^{-t}(1-t^2)$  (x)  $e^{2t} \sinh t$

(xi)  $e^t (\cosh 2t - \sin t)$  (xii)  $e^{2t}(3t^5 - \cos 4t)$  (xiii)  $e^{-t} \sin 4t \cos 2t$  (xiv)  $e^{-3t}\sin 5t \sin 3t$

Change of scale property:

If  $L\{f(t)\} = \bar{f}(s)$ , then

$$L\{f(at)\} = \frac{1}{a}\bar{f}\left(\frac{s}{a}\right)$$

Laplace Transforms of Derivatives:

If  $L\{f(t)\} = \bar{f}(s)$  and  $f'(t)$  is continuous, then

$$L\{f'(t)\} = s\bar{f}(s) - f(0) \quad *$$

$$L\{f''(t)\} = s^2\bar{f}(s) - sf'(0) - f''(0) \quad *$$

$$L\{f'''(t)\} = s^3\bar{f}(s) - s^2f'(0) - sf''(0) - f'''(0) \quad *$$

and so on

Laplace Transforms of Integrals:

If  $L\{f(t)\} = \bar{f}(s)$ , then  $L\left\{\int_0^t f(u)du\right\} = \frac{1}{s}\bar{f}(s) \quad *$

Laplace Transforms of  $t^n f(t)$  : (Multiplication by  $t, t^2, \dots$ )

If  $L\{f(t)\} = \bar{f}(s)$ , then for a positive integer  $n$

$$L\{t^n f(t)\} = (-1)^n \frac{d^n}{ds^n} \left\{ \bar{f}(s) \right\}$$

Particular ly, for  $n = 1, L\{t f(t)\} = (-1)^1 \frac{d^1}{ds^1} \left\{ \bar{f}(s) \right\} = -\frac{d}{ds} \left\{ \bar{f}(s) \right\} \quad *$

for  $n = 2, L\{t^2 f(t)\} = (-1)^2 \frac{d^2}{ds^2} \left\{ \bar{f}(s) \right\} = \frac{d^2}{ds^2} \left\{ \bar{f}(s) \right\} \quad *$

Laplace transform of  $\frac{f(t)}{t}$  (division by  $t$ )

If  $L\{f(t)\} = \bar{f}(s)$ , then  $L\left(\frac{f(t)}{t}\right) = \int_s^\infty \bar{f}(s) ds \quad *$

**Ex 3 : Find the Laplace transforms of the following functions :** (i)  $t \sin t$  (ii)  $t \cos t$  (iii)  $t^2 \sin t$  (iv)  $t^2 \cos t$

(v)  $t \sin^2 t$  (vi)  $t \cos 2t$  (vii)  $t e^{-t} \sin 4t$  (viii)  $t \sin 3t \cdot \cos 2t$  (ix)  $t e^{-t} \cos t$  (x)  $t^2 \sin t$

(i) Here  $f(t) = \sin t$

$$\therefore L(f(t)) = L(\sin t) = \frac{1}{s^2 + 1} = \bar{f}(s)$$

So, by using result  $L(t f(t)) = -\frac{d}{ds} \left( \bar{f}(s) \right)$ , we get

$$L(t \sin t) = -\frac{d}{ds} \left( \frac{1}{s^2 + 1} \right) = -\frac{0 - 2s}{(s^2 + 1)^2} = \frac{2s}{(s^2 + 1)^2} \text{ (by division rule)}$$

(ii) Here  $f(t) = \cos t$

$$\therefore L(f(t)) = L(\cos t) = \frac{s}{s^2 + 1} = \bar{f}(s)$$

so, by using result  $L(t f(t)) = -\frac{d}{ds}(\bar{f}(s))$ , we get

$$L(t \cos t) = -\frac{d}{ds} \left( \frac{s}{s^2 + 1} \right) = -\left( \frac{1 \cdot (s^2 + 1) - s \cdot 2s}{(s^2 + 1)^2} \right) = \frac{s^2 - 1}{(s^2 + 1)^2}$$

(iii) Here  $f(t) = \sin t$

$$\therefore L(f(t)) = L(\sin t) = \frac{1}{s^2 + 1} = \bar{f}(s)$$

so, by using result  $L(t^2 f(t)) = \frac{d^2}{ds^2}(\bar{f}(s))$ , we get

$$\begin{aligned} L(t^2 \sin t) &= \frac{d^2}{ds^2} \left( \frac{1}{s^2 + 1} \right) = \frac{d}{ds} \left( \frac{d}{ds} \left( \frac{1}{s^2 + 1} \right) \right) \\ &= \frac{d}{ds} \left( \frac{2s}{(s^2 + 1)^2} \right) = \frac{2 \cdot (s^2 + 1)^2 - 2s \cdot 2(s^2 + 1) \cdot 2s}{(s^2 + 1)^4} \\ &= \frac{(s^2 + 1) \{ 2(s^2 + 1) - 8s^2 \}}{(s^2 + 1)^4} = \frac{2 - 6s^2}{(s^2 + 1)^3} \end{aligned}$$

(iv) Here  $f(t) = \cos t$

$$\therefore L(f(t)) = L(\cos t) = \frac{s}{s^2 + 1} = \bar{f}(s)$$

so, by using result  $L(t^2 f(t)) = \frac{d^2}{ds^2}(\bar{f}(s))$ , we get

$$\begin{aligned} L(t^2 \cos t) &= \frac{d^2}{ds^2} \left( \frac{s}{s^2 + 1} \right) = \frac{d}{ds} \left( \frac{d}{ds} \left( \frac{s}{s^2 + 1} \right) \right) \\ &= \frac{d}{ds} \left( \frac{1 \cdot (s^2 + 1) - s \cdot 2s}{(s^2 + 1)^2} \right) = \frac{d}{ds} \frac{1 - s^2}{(s^2 + 1)^2} \\ &= \frac{-2s \cdot (s^2 + 1)^2 - (1 - s^2) \cdot 2(s^2 + 1) \cdot 2s}{(s^2 + 1)^4} \\ &= \frac{(s^2 + 1) \{ -2s^3 - 2s - 4s + 4s^3 \}}{(s^2 + 1)^4} = \frac{2s^3 - 6s}{(s^2 + 1)^3} \end{aligned}$$

(v) Here  $f(t) = \sin^2 t$

$$\therefore L(\sin^2 t) = L\left(\frac{1 - \cos 2t}{2}\right) = \frac{1}{2}\left(\frac{1}{s} - \frac{s}{s^2 + 4}\right) = \bar{f}(s)$$

So, by using result  $L(t f(t)) = -\frac{d}{ds}(\bar{f}(s))$ , we get

$$\begin{aligned} L(t \sin^2 t) &= -\frac{d}{ds} \left\{ \frac{1}{2} \left( \frac{1}{s} - \frac{s}{s^2 + 4} \right) \right\} = -\frac{1}{2} \frac{d}{ds} \left( \frac{1}{s} - \frac{s}{s^2 + 4} \right) \\ &= -\frac{1}{2} \left( -\frac{1}{s^2} - \frac{1 \cdot s^2 + 4 - s \cdot 2s}{(s^2 + 4)^2} \right) = \frac{1}{2s^2} + \frac{4 - s^2}{2(s^2 + 4)^2} \end{aligned}$$

(vi) Here  $f(t) = \cos 2t$

$$\therefore L(\cos 2t) = \frac{s}{s^2 + 4} = \bar{f}(s)$$

So, by using result  $L(t f(t)) = -\frac{d}{ds}(\bar{f}(s))$ , we get

$$L(t \cos 2t) = -\frac{d}{ds} \left( \frac{s}{s^2 + 4} \right) = -\frac{1 \cdot s^2 + 4 - s \cdot 2s}{(s^2 + 4)^2} = \frac{4 - s^2}{(s^2 + 4)^2}$$

(vii) We have  $L(\sin 4t) = \frac{4}{s^2 + 16}$

So, by using result  $L(t f(t)) = -\frac{d}{ds}(\bar{f}(s))$ , we get

$$L(t \sin 4t) = -\frac{d}{ds} \left( \frac{4}{s^2 + 16} \right) = -\frac{0 - 4 \cdot 2s}{(s^2 + 16)^2} = \frac{8s}{(s^2 + 16)^2}$$

Now by using first shifting property, we get

$$L(e^{-t} t \sin 4t) = \frac{8(s+1)}{[(s+1)^2 + 16]^2} = \frac{8(s+1)}{(s^2 + 2s + 17)^2}$$

(ix) We have  $L(\cosh t) = \frac{s}{s^2 - 1}$

So, by using result  $L(t f(t)) = -\frac{d}{ds}(\bar{f}(s))$ , we get

$$L(t \cosh t) = -\frac{d}{ds} \left( \frac{s}{s^2 - 1} \right) = -\frac{1 \cdot s^2 - 1 - s \cdot 2s}{(s^2 - 1)^2} = \frac{s^2 + 1}{(s^2 - 1)^2}$$

Now by using first shifting property, we get

$$L(e^{-t} t \cosh t) = \frac{(s+1)^2 + 1}{[(s+1)^2 - 1]^2} = \frac{s^2 + 2s + 2}{(s^2 + 2s)^2}$$

(viii) Here  $f(t) = \sin 3t \cdot \cos 2t$

$$\begin{aligned} \therefore L(\sin 3t \cdot \cos 2t) &= \frac{1}{2} L(2 \sin 3t \cdot \cos 2t) \\ &= \frac{1}{2} L(\sin 5t + \sin t) = \frac{1}{2} \left( \frac{5}{s^2 + 25} + \frac{1}{s^2 + 1} \right) = \bar{f}(s) \end{aligned}$$

So, using result  $L(t f(t)) = -\frac{d}{ds}(\bar{f}(s))$ , we get

$$\begin{aligned} L(t \cdot \sin 3t \cos 2t) &= -\frac{d}{ds} \frac{1}{2} \left( \frac{5}{s^2 + 25} + \frac{1}{s^2 + 1} \right) = -\frac{1}{2} \left( \frac{0 - 5 \cdot 2s}{(s^2 + 25)^2} + \frac{0 - 2s}{(s^2 + 1)^2} \right) \\ &= -\frac{1}{2} \left( \frac{-10s}{(s^2 + 25)^2} + \frac{-2s}{(s^2 + 1)^2} \right) = \frac{5s}{(s^2 + 25)^2} + \frac{s}{(s^2 + 1)^2} \end{aligned}$$

(x) Here  $f(t) = \sin at$

$$\therefore L(\sin at) = \frac{a}{s^2 + a^2} = \bar{f}(s)$$

So by using result  $L(t^2 f(t)) = \frac{d^2}{ds^2}(\bar{f}(s))$ , we get

$$\begin{aligned} L(t^2 \sin at) &= \frac{d^2}{ds^2} \left( \frac{a}{s^2 + a^2} \right) = \frac{d}{ds} \left( \frac{d}{ds} \left( \frac{a}{s^2 + a^2} \right) \right) \\ &= \frac{d}{ds} \left( \frac{0 - a \cdot 2s}{(s^2 + a^2)^2} \right) = -2a \frac{d}{ds} \left( \frac{s}{(s^2 + a^2)^2} \right) \\ &= -2a \left( \frac{1 \cdot (s^2 + a^2)^2 - s \cdot 2(s^2 + a^2) \cdot 2s}{(s^2 + a^2)^4} \right) \\ &= \frac{-2a(s^2 + a^2)(s^2 + a^2 - 4s^2)}{(s^2 + a^2)^4} = \frac{-2a(a^2 - 3s^2)}{(s^2 + a^2)^3} \end{aligned}$$

### Exercises-3

Find Laplace transforms of the following functions: (i)  $t \sin 2t$  (ii)  $t \cos 3t$  (iii)  $t^2 \cos 2t$  (iv)  $t e^t \sin 2t$

(v)  $t e^{-2t} \cos t$  (vi)  $t e^{-t} \sinh 2t$  (vii)  $t \cos 4t \cos t$  (viii)  $t^2 e^{-t} \cos t$

**Ex 4 : Find the Laplace transforms of the following functions.**

(i)  $\frac{1 - e^t}{t}$ , (ii)  $\frac{e^{-t} - 1}{t}$ , (iii)  $\frac{e^t - e^{-t}}{t}$ , (iv)  $\frac{e^{-at} - e^{-bt}}{t}$

(v)  $\frac{1 - \cos 2t}{t}$ , (vi)  $\frac{\cos 2t - \cos 3t}{t}$ , (vii)  $\frac{\sin t}{t}$  (viii)  $\frac{\sin^2 t}{t}$

(ix)  $\frac{e^{-t} \sin t}{t}$ , (x)  $\frac{\sin at}{t}$ , (xi)  $\frac{e^{at} - \cos bt}{t}$

Sol<sup>n</sup>:(i) Here  $f(t) = 1 - e^{-t}$ 

$$\bar{f}(s) = L(1 - e^{-t}) = \frac{1}{s} - \frac{1}{s-1}$$

$$\begin{aligned} \therefore L\left(\frac{1 - e^{-t}}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \left(\frac{1}{s} - \frac{1}{s-1}\right) ds \\ &= [\log s - \log(s-1)]_s^\infty = \left[\log \frac{s}{s-1}\right]_s^\infty = \log \frac{s-1}{s} \end{aligned}$$

(ii) Here  $f(t) = e^{-t} - 1$ 

$$\bar{f}(s) = L(e^{-t} - 1) = \frac{1}{s+1} - \frac{1}{s}$$

$$\begin{aligned} \therefore L\left(\frac{e^{-t} - 1}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \left(\frac{1}{s+1} - \frac{1}{s}\right) ds \\ &= [\log(s+1) - \log s]_s^\infty = \left[\log \frac{s+1}{s}\right]_s^\infty = \log \frac{s}{s+1} \end{aligned}$$

(iii) Here  $f(t) = e^t - e^{-t}$ 

$$\bar{f}(s) = L(e^t - e^{-t}) = \frac{1}{s-1} - \frac{1}{s+1}$$

$$\begin{aligned} \therefore L\left(\frac{e^t - e^{-t}}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \left(\frac{1}{s-1} - \frac{1}{s+1}\right) ds \\ &= [\log(s-1) - \log(s+1)]_s^\infty = \left[\log \frac{s-1}{s+1}\right]_s^\infty = \log \frac{s+1}{s-1} \end{aligned}$$

(iv) Here  $f(t) = e^{-at} - e^{-bt}$ 

$$\bar{f}(s) = L(e^{-at} - e^{-bt}) = \frac{1}{s+a} - \frac{1}{s+b}$$

$$\begin{aligned} \therefore L\left(\frac{e^{-at} - e^{-bt}}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \left(\frac{1}{s+a} - \frac{1}{s+b}\right) ds \\ &= [\log(s+a) - \log(s+b)]_s^\infty = \left[\log \frac{s+a}{s+b}\right]_s^\infty = \log \frac{s+b}{s+a} \end{aligned}$$



(v) Here  $f(t) = 1 - \cos 2t$

$$\begin{aligned}\bar{f}(s) &= L(1 - \cos 2t) = \frac{1}{s} - \frac{s}{s^2 + 4} \\ \therefore L\left(\frac{1 - \cos 2t}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \left(\frac{1}{s} - \frac{s}{s^2 + 4}\right) ds \\ &= \left[ \log s - \frac{1}{2} \log(s^2 + 4) \right]_s^\infty = \left[ \log s - \log \sqrt{s^2 + 4} \right]_s^\infty \\ &= \left[ \log \frac{s}{\sqrt{s^2 + 4}} \right]_s^\infty = \log \frac{\sqrt{s^2 + 4}}{s}\end{aligned}$$

(vi) Here  $f(t) = \cos 2t - \cos 3t$

$$\begin{aligned}\bar{f}(s) &= L(\cos 2t - \cos 3t) = \frac{s}{s^2 + 4} - \frac{s}{s^2 + 9} \\ \therefore L\left(\frac{\cos 2t - \cos 3t}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \left(\frac{s}{s^2 + 4} - \frac{s}{s^2 + 9}\right) ds \\ &= \left[ \frac{1}{2} \log(s^2 + 4) - \frac{1}{2} \log(s^2 + 9) \right]_s^\infty \\ &= \frac{1}{2} \log \left[ \frac{s^2 + 4}{s^2 + 9} \right]_s^\infty = \frac{1}{2} \log \left( \frac{s^2 + 9}{s^2 + 4} \right)\end{aligned}$$

(vii) Here  $f(t) = \sin t$

$$\begin{aligned}\bar{f}(s) &= L(\sin t) = \frac{1}{s^2 + 1} \\ \therefore L\left(\frac{\sin t}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \frac{1}{s^2 + 1} ds = \left[ \tan^{-1} s \right]_s^\infty \\ &= \tan^{-1} \infty - \tan^{-1} s = \frac{\pi}{2} - \tan^{-1} s = \cot^{-1} s\end{aligned}$$

(viii) Here  $f(t) = \sin^2 t$ ,  $\bar{f}(s) = L(\sin^2 t) = L\left(\frac{1 - \cos 2t}{2}\right)$

$$\begin{aligned}&= \frac{1}{2} \left( \frac{1}{s} - \frac{s}{s^2 + 4} \right) \\ \therefore L\left(\frac{\sin^2 t}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \frac{1}{2} \int_s^\infty \left( \frac{1}{s} - \frac{s}{s^2 + 4} \right) ds = \frac{1}{2} \left[ \log s - \frac{1}{2} \log(s^2 + 4) \right]_s^\infty \\ &= \frac{1}{2} \left[ \log s - \log \sqrt{s^2 + 4} \right]_s^\infty = \frac{1}{2} \log \left[ \frac{s}{\sqrt{s^2 + 4}} \right]_s^\infty = \frac{1}{2} \log \left( \frac{\sqrt{s^2 + 4}}{s} \right)\end{aligned}$$

(ix) Here  $f(t) = e^{-t} \sin t$

$$\bar{f}(s) = L(e^{-t} \sin t) = \frac{1}{(s+1)^2 + 1} \quad (\text{by shifting rule})$$

$$\begin{aligned} \therefore L\left(\frac{e^{-t} \sin t}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \frac{1}{(s+1)^2 + 1} ds \\ &= \left[ \tan^{-1}(s+1) \right]_s^\infty = \tan^{-1}\infty - \tan^{-1}(s+1) \\ &= \frac{\pi}{2} - \tan^{-1}(s+1) = \cot^{-1}(s+1) \end{aligned}$$

(x) Here  $f(t) = \sin at$

$$\bar{f}(s) = L(\sin at) = \frac{a}{s^2 + a^2}$$

$$\begin{aligned} \therefore L\left(\frac{\sin at}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \frac{a}{s^2 + a^2} ds = a \cdot \left[ \frac{1}{a} \tan^{-1}\left(\frac{s}{a}\right) \right]_s^\infty \\ &= \left[ \tan^{-1}\left(\frac{s}{a}\right) \right]_s^\infty = \tan^{-1}\infty - \tan^{-1}\left(\frac{s}{a}\right) \\ &= \frac{\pi}{2} - \tan^{-1}\left(\frac{s}{a}\right) = \cot^{-1}\left(\frac{s}{a}\right) \end{aligned}$$

(xi) Here  $f(t) = e^{at} - \cos bt$

$$\bar{f}(s) = L(e^{at} - \cos bt) = \frac{1}{s-a} - \frac{s}{s^2 + b^2}$$

$$\begin{aligned} \therefore L\left(\frac{e^{at} - \cos bt}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty \left( \frac{1}{s-a} - \frac{s}{s^2 + b^2} \right) ds \\ &= \left[ \log(s-a) - \frac{1}{2} \log(s^2 + b^2) \right]_s^\infty = \left[ \log(s-a) - \log \sqrt{s^2 + b^2} \right]_s^\infty \\ &= \left[ \log \frac{s-a}{\sqrt{s^2 + b^2}} \right]_s^\infty = \log \frac{\sqrt{s^2 + b^2}}{s-a} \end{aligned}$$

#### Exercises-4

Find Laplace transforms of the following functions:

(i)  $\frac{1 - e^{at}}{t}$       (ii)  $\frac{e^{at} - e^{bt}}{t}$       (iii)  $\frac{1 - \cos t}{t}$       (iv)  $\frac{\cos at - \cos bt}{t}$

(v)  $\frac{\sin 2t}{t}$       (vi)  $\frac{e^t \sin t}{t}$       (vii)  $\frac{e^{-t} - e^{-3t}}{t}$

Ex 5 : Find the Laplace transforms of the following functions :

$$(i) \int_0^t e^{-t} \cos t \, dt \quad (ii) \int_0^t \frac{\sin t}{t} \, dt \quad (iii) \int_0^t e^t \left( \frac{\sin t}{t} \right) dt$$

$$(iv) \int_0^t \frac{\cos at - \cos bt}{t} \, dt$$

**Sol<sup>n</sup>:**

(i) Here  $f(t) = e^{-t} \cos t$

$$L\{f(t)\} = L(e^{-t} \cos t) = \frac{s+1}{(s+1)^2 + 1} = \frac{s+1}{s^2 + 2s + 2} = \bar{f}(s)$$

$$\therefore L\left(\int_0^t e^{-t} \cos t \, dt\right) = \frac{\bar{f}(s)}{s} = \frac{1}{s} \cdot \frac{s+1}{s^2 + 2s + 2} = \frac{s+1}{s(s^2 + 2s + 2)}$$

(ii) Here  $f(t) = \frac{\sin t}{t}$

$$L\left(\frac{\sin t}{t}\right) = \int_s^\infty \bar{f}(s) \, ds = \int_s^\infty L(\sin t) \, ds \quad (\text{by division rule})$$

$$= \int_s^\infty \frac{1}{s^2 + 1} \, ds = [\tan^{-1} s]_s^\infty = \tan^{-1} \infty - \tan^{-1} s$$

$$= \frac{\pi}{2} - \tan^{-1} s = \cot^{-1} s = \bar{f}(s)$$

$$\therefore L\left(\int_0^t \frac{\sin t}{t} \, dt\right) = \frac{\bar{f}(s)}{s} = \frac{\cot^{-1} s}{s}$$

(iii) Here  $f(t) = \left(e^t \left(\frac{\sin t}{t}\right)\right)$

$$\text{Now } L\left(\frac{\sin t}{t}\right) = \int_s^\infty \bar{f}(s) \, ds = \int_s^\infty L(\sin t) \, ds \quad (\text{by division rule})$$

$$= \int_s^\infty \frac{1}{s^2 + 1} \, ds = [\tan^{-1} s]_s^\infty = \tan^{-1} \infty - \tan^{-1} s$$

$$= \frac{\pi}{2} - \tan^{-1} s = \cot^{-1} s$$

$$\text{So, } L\left(e^t \left(\frac{\sin t}{t}\right)\right) = \cot^{-1}(s-1) = \bar{f}(s) \quad (\text{by first shifting rule})$$

$$\therefore L\left(\int_0^t e^t \left(\frac{\sin t}{t}\right) \, dt\right) = \frac{\bar{f}(s)}{s} = \frac{\cot^{-1}(s-1)}{s}$$

$$(iv) \quad \text{Here } f(t) = \frac{\cos at - \cos bt}{t}$$

$$\begin{aligned} \text{Now } L\left(\frac{\cos at - \cos bt}{t}\right) &= \int_s^\infty \bar{f}(s) ds = \int_s^\infty L(\cos at - \cos bt) ds \\ &= \int_s^\infty \left(\frac{s}{s^2 + a^2} - \frac{s}{s^2 + b^2}\right) ds \\ &= \left[\frac{1}{2} \log(s^2 + a^2) - \frac{1}{2} \log(s^2 + b^2)\right]_s^\infty \\ &= \frac{1}{2} \left[\log\left(\frac{s^2 + a^2}{s^2 + b^2}\right)\right]_s^\infty = \frac{1}{2} \log\left(\frac{s^2 + b^2}{s^2 + a^2}\right) = \bar{f}(s) \\ \therefore L\left(\int_0^t \frac{\cos at - \cos bt}{t} dt\right) &= \frac{\bar{f}(s)}{s} = \frac{1}{2s} \log\left(\frac{s^2 + b^2}{s^2 + a^2}\right) \end{aligned}$$

**Exercise-5**

Find Laplace transforms of the following functions:

$$(i) \int_0^t e^{2t} \sin t dt \quad (ii) \int_0^t \sin 2t \cos t dt \quad (iii) \int_0^t t \sin 2t dt$$

$$(iv) \int_0^t t e^{-t} \sin 4t dt \quad (v) \int_0^t \frac{\cos 2t - \cos 3t}{t} dt$$

(vi) By using the Laplace transform of  $\sin at$ , find Laplace transform of  $\cos at$ .

Ex 6: By using the Laplace transform of  $\cos at$ , find Laplace transform of  $\sin at$ .

$$\text{Sol}^n : \text{Let } f(t) = \cos at. \text{ Then } L(f(t)) = \frac{s}{s^2 + a^2} = \bar{f}(s)$$

$$\text{Now } f'(t) = -a \sin at$$

$$\Rightarrow L(f'(t)) = -a L(\sin at)$$

$$\Rightarrow L(\sin at) = -\frac{1}{a} L(f'(t))$$

$$= -\frac{1}{a} \left( s \bar{f}(s) - f(0) \right) \quad (\text{by Laplace transform of derivative})$$

$$= -\frac{1}{a} \left( s \cdot \frac{s}{s^2 + a^2} - 1 \right) = -\frac{1}{a} \left( \frac{s^2 - s^2 - a^2}{s^2 + a^2} \right)$$

$$= \frac{a}{s^2 + a^2}$$

**Evaluation of integrals using def<sup>n</sup> of Laplace Transform :**

We know from definition of Laplace Transform that

$$L\{f(t)\} = \int_0^{\infty} e^{-st} f(t) dt \text{ where } s \text{ is real or complex}$$

Now we shall evaluate the integrals using above result.

**Ex 6: Evaluate following integrals:**

$$(i) \int_0^{\infty} e^{-t} t dt$$

$$\begin{aligned} \text{Sol}^n : \int_0^{\infty} e^{-t} t dt &= L(t) \text{ where } s = 1, \text{ by definition} \\ &= \frac{1}{s^2} = \frac{1}{1} = 1 \end{aligned}$$

$$(ii) \int_0^{\infty} t e^{-2t} \sin t dt$$

$$\begin{aligned} \text{Sol}^n : \int_0^{\infty} t e^{-2t} \sin t dt &= L(t \sin t) \text{ where } s = 2, \text{ by definition} \\ &= -\frac{d}{ds} \left( \frac{1}{s^2 + 1} \right) = \frac{2s}{(s^2 + 1)^2} \\ &= \frac{2 \times 2}{(2^2 + 1)^2} = \frac{4}{25} \end{aligned}$$

$$(iii) \int_0^{\infty} t e^{3t} \cos t dt = L(t \cos t) \text{ where } s = -3, \text{ by definition}$$

$$\begin{aligned} &= -\frac{d}{ds} \left( \frac{s}{s^2 + 1} \right) = -\left( \frac{1 \cdot s^2 + 1 - s \cdot 2s}{(s^2 + 1)^2} \right) \\ &= \frac{s^2 - 1}{(s^2 + 1)^2} = \frac{9 - 1}{(9 + 1)^2} = \frac{8}{100} = \frac{2}{25} \end{aligned}$$

**Exercise - 6****Evaluate the following integrals :**

$$(i) \int_0^{\infty} t^2 e^t dt \quad (ii) \int_0^{\infty} t e^{-t} \sin 2t dt \quad (iii) \int_0^{\infty} e^{-2t} t \cos t dt$$

$$(iv) \int_0^{\infty} \frac{e^{-at} - e^{-bt}}{t} dt \quad (v) \int_0^{\infty} \frac{e^{-t} \sin^2 t}{t} dt$$

**Inverse Laplace Transforms:**

As before , if  $L\{f(t)\} = \bar{f}(s)$ , then  $L^{-1}\{\bar{f}(s)\} = f(t)$

Here , the symbol  $L^{-1}$  stands for inverse laplace

Formula :

$$(i) L^{-1}\left(\frac{1}{s}\right) = 1$$

$$(ii) L^{-1}\left(\frac{1}{s-a}\right) = e^{at}$$

$$(iii) L^{-1}\left(\frac{1}{s^n}\right) = \frac{t^{n-1}}{(n-1)!}, n = 1,2,3,\dots$$

$$(iv) L^{-1}\left(\frac{1}{(s-a)^n}\right) = \frac{e^{at} t^{n-1}}{(n-1)!}, n = 1,2,3,\dots$$

$$(v) L^{-1}\left(\frac{a}{s^2 + a^2}\right) = \sin at$$

$$(vi) L^{-1}\left(\frac{1}{s^2 + a^2}\right) = \frac{1}{a} \sin at$$

$$(vii) L^{-1}\left(\frac{s}{s^2 + a^2}\right) = \cos at$$

$$(viii) L^{-1}\left(\frac{a}{s^2 - a^2}\right) = \sinh at$$

$$(ix) L^{-1}\left(\frac{1}{s^2 - a^2}\right) = \frac{1}{a} \sinh at$$

$$(x) L^{-1}\left(\frac{s}{s^2 - a^2}\right) = \cosh at$$

$$(xi) L^{-1}\left(\frac{a}{(s-b)^2 + a^2}\right) = e^{bt} \sin at$$

$$(xii) L^{-1}\left(\frac{1}{(s-b)^2 + a^2}\right) = \frac{1}{a} e^{bt} \sin at$$

$$(xiii) L^{-1}\left(\frac{s-b}{(s-b)^2 + a^2}\right) = e^{bt} \cos at$$

$$(xiv) L^{-1}\left(\frac{s}{(s^2 + b^2)^2}\right) = \frac{1}{2b} t \sin bt$$

Ex - 1 : Find inverse Laplace transform of the following :

$$(i) \frac{1}{s^4}, (ii) \frac{2}{s-1}, (iii) \frac{3}{s+5}, (iv) \frac{2s}{s^2+4}, (v) \frac{s-1}{s^2+9}$$

$$\text{Sol}^n : (i) \mathcal{L}^{-1}\left(\frac{1}{s^4}\right) = \frac{t^{4-1}}{(4-1)!} = \frac{t^3}{3!} = \frac{t^3}{6}$$

$$(ii) \mathcal{L}^{-1}\left(\frac{2}{s-1}\right) = 2\mathcal{L}^{-1}\left(\frac{1}{s-1}\right) = 2e^t$$

$$(iii) \mathcal{L}^{-1}\left(\frac{3}{s+5}\right) = 3\mathcal{L}^{-1}\left(\frac{1}{s+5}\right) = 3e^{-5t}$$

$$(iv) \mathcal{L}^{-1}\left(\frac{2s}{s^2+4}\right) = 2\mathcal{L}^{-1}\left(\frac{s}{s^2+4}\right) = 2\cos 2t$$

$$(v) \mathcal{L}^{-1}\left(\frac{s-1}{s^2+9}\right) = \mathcal{L}^{-1}\left(\frac{s}{s^2+9}\right) - \mathcal{L}^{-1}\left(\frac{1}{s^2+9}\right) = \cos 3t - \frac{1}{3}\sin 3t$$

Ex - 2 : Find inverse Laplace transform of the following :

$$(i) \frac{1}{s^2-2s+5}, (ii) \frac{s}{s^2+2s+10}, (iii) \frac{3s+7}{s^2-2s-3}$$

$$\begin{aligned} \text{Sol}^n : (i) \mathcal{L}^{-1}\left(\frac{1}{s^2-2s+5}\right) &= \mathcal{L}^{-1}\left(\frac{1}{s^2-2s+1-1+5}\right) \\ &= \mathcal{L}^{-1}\left(\frac{1}{(s-1)^2+4}\right) = \frac{1}{2}e^t \sin 2t \end{aligned}$$

$$\begin{aligned} (ii) \mathcal{L}^{-1}\left(\frac{s}{s^2+2s+10}\right) &= \mathcal{L}^{-1}\left(\frac{s}{s^2+2s+1-1+10}\right) \\ &= \mathcal{L}^{-1}\left(\frac{s}{(s+1)^2+9}\right) = \mathcal{L}^{-1}\left(\frac{s+1-1}{(s+1)^2+9}\right) \\ &= \mathcal{L}^{-1}\left(\frac{s+1}{(s+1)^2+9}\right) - \mathcal{L}^{-1}\left(\frac{1}{(s+1)^2+9}\right) \\ &= e^{-t} \cos 3t - \frac{1}{3}e^{-t} \sin 3t \end{aligned}$$

$$\begin{aligned} (iii) \mathcal{L}^{-1}\left(\frac{3s+7}{s^2-2s-3}\right) &= \mathcal{L}^{-1}\left(\frac{3s}{s^2-2s-3}\right) + \mathcal{L}^{-1}\left(\frac{7}{s^2-2s-3}\right) \\ &= \mathcal{L}^{-1}\left(\frac{3s}{(s-1)^2-4}\right) + \mathcal{L}^{-1}\left(\frac{7}{(s-1)^2-4}\right) = \mathcal{L}^{-1}\left(\frac{3(s-1+1)}{(s-1)^2-4}\right) + \mathcal{L}^{-1}\left(\frac{7}{(s-1)^2-4}\right) \\ &= \mathcal{L}^{-1}\left(\frac{3(s-1)}{(s-1)^2-4}\right) + \mathcal{L}^{-1}\left(\frac{10}{(s-1)^2-4}\right) \\ &= 3e^t \cosh 2t + 10 \cdot \frac{1}{2}e^t \sinh 2t \\ &= 3e^t \cosh 2t + 5e^t \sinh 2t \end{aligned}$$

Reference Books:

Higher engineering mathematics By Dr B.S. Grewal (khanna publishers)